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This textbook – a result of the author's many years of research and teaching – brings together diverse concepts of the versatile tool of multibody dynamics, combining the efforts of many researchers in the field of mechanics.

Providing a unique bridge between the foundations of analytical mechanics and application to multi-body dynamical systems, this textbook is particularly well suited for graduate students seeking an understanding of the theoretical underpinnings of analytical mechanics, as well as modern task space approaches for representing the resulting dynamics that can be exploited for real-world problems in areas such as biomechanics and robotics. Established principles in mechanics are presented in a thorough and modern way. The chapters build up from general mathematical foundations, an extensive treatment of kinematics, and then to a rigorous treatment of conservation and variational principles in mechanics. Parallels are drawn between the different approaches, providing the reader with insights that unify his or her understanding of analytical dynamics. Additionally, a unique treatment is presented on task space dynamical formulations that map traditional configuration space representations into more intuitive geometric spaces.

This textbook provides graduate and advanced undergraduate students with a comprehensive introduction to the application of basic principles and concepts for physical and engineering acoustics. Many of the chapters are independent, and all build from introductory to more sophisticated material. Written by a well-known textbook author with 39 years of experience performing research, teaching, and mentoring in the field, it is specially designed to provide maximum support for learning. Derivations are rigorous and logical, with thorough explanations of operations that are not obvious. Many of the derivations and examples have not previously appeared in print. Important concepts are discussed for their physical implications and implementation. Many of the 56 examples are mini case studies that address systems students will find to be interesting and motivating for continued study. The example solutions address both the significance of the example and the reasoning underlying the formulation. Tasks that require computational work are fully explained. This volume contains 168 homework exercises, accompanied by a detailed solutions manual for instructors. Building on the foundation provided in Volume I: Fundamentals, this text offers a knowledge base that will enable the reader to begin undertaking research and to work in the core areas of acoustics.

Advanced Dynamics is a broad and detailed description of the analytical tools of dynamics as used in mechanical and aerospace engineering. The strengths and weaknesses of various approaches are discussed, and particular emphasis is placed on learning through problem solving. The book begins with a thorough review of vectorial dynamics and goes on to cover Lagrange's and Hamilton's equations as well as less familiar topics such as impulse response, and differential forms and integrability. Techniques are described that provide a considerable improvement in computational efficiency over the standard classical methods, especially when applied to complex dynamical systems. The treatment of numerical analysis includes discussions of numerical stability and constraint stabilization. Many worked examples and homework problems are provided. The book is intended for use on graduate courses on dynamics, and will also appeal to researchers in mechanical and aerospace engineering.

'Advanced Engineering Dynamics' bridges the gap between elementary dynamics and advanced specialist applications in engineering. It begins with a reappraisal of Newtonian principles before expanding into analytical dynamics typified by the methods of Lagrange and by Hamilton's Principle and rigid body dynamics. Four distinct vehicle types (satellites, rockets, aircraft and cars) are examined highlighting different aspects of dynamics in each case. Emphasis is placed on impact and one dimensional wave propagation before extending the study into three dimensions. Robotics is then looked at in detail, forging a link between conventional dynamics and the highly specialised and distinctive approach used in robotics. The text finishes with an excursion into the Special Theory of Relativity mainly to define the boundaries of Newtonian Dynamics but also to re-appraise the fundamental definitions. Through its examination of specialist applications highlighting the many different aspects of dynamics this text provides an excellent insight into advanced systems without restricting itself to a particular discipline. The result is essential reading for all those requiring a general understanding of the more advanced aspects of engineering dynamics.

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